



13th CONFERENCE on Active Noise and Vibration Control Methods 12-14.06.2017

OPERATIONAL MODAL ANALYSIS OF THE LARGE STRUCTURE WORKPIECES

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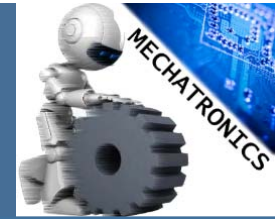
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Machining of large workpieces



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Actual research



Research grant TANGO1/266350/NCBR/2015

***„ Application of chosen mechatronic solutions to
surveillance of the high-dimensional workpieces cutting
process on multi axial machining centres
2015-2018”***





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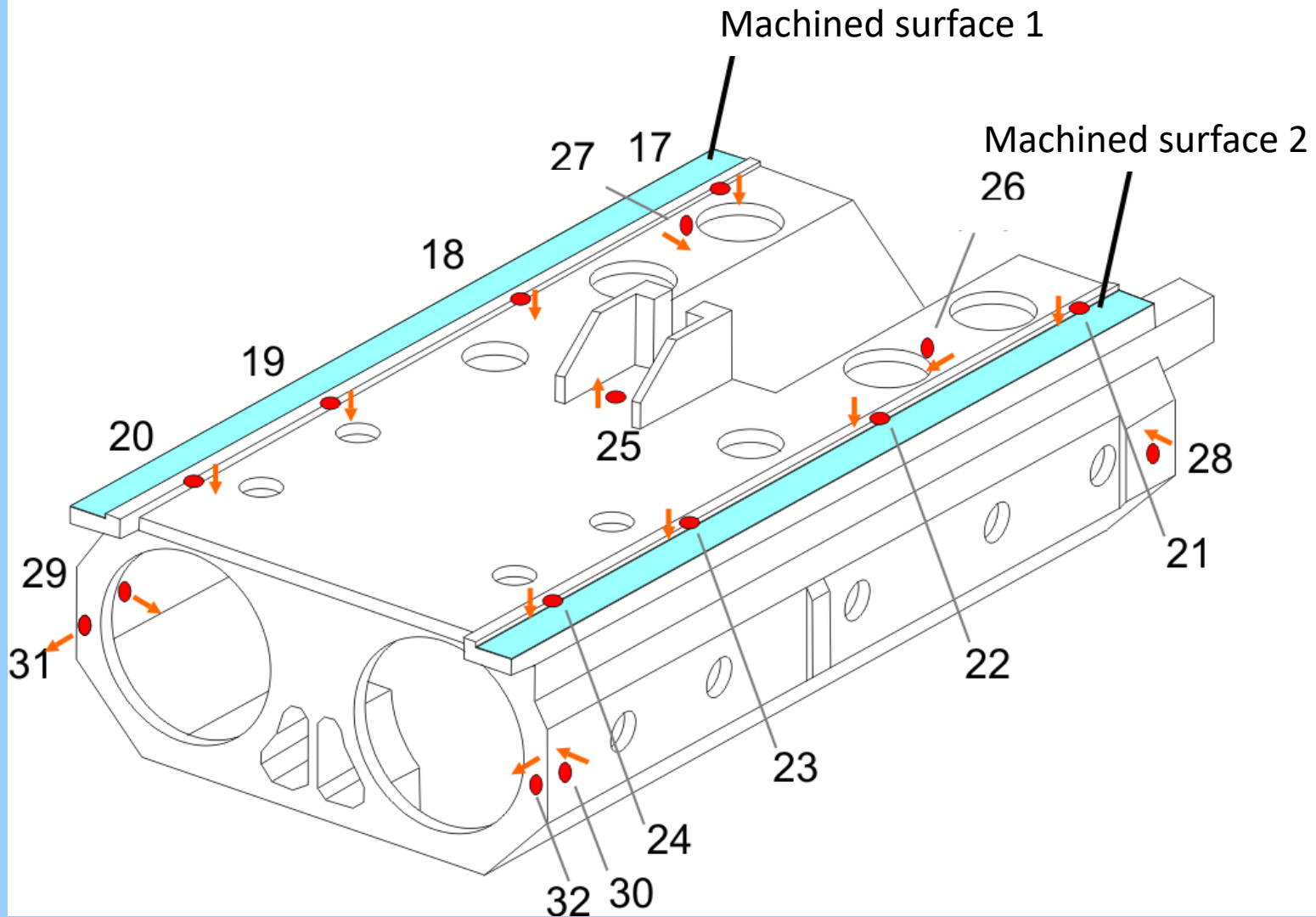
The workpiece



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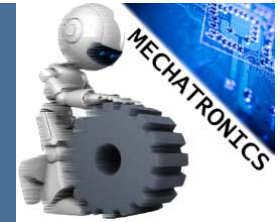


Acceleration sensors placements

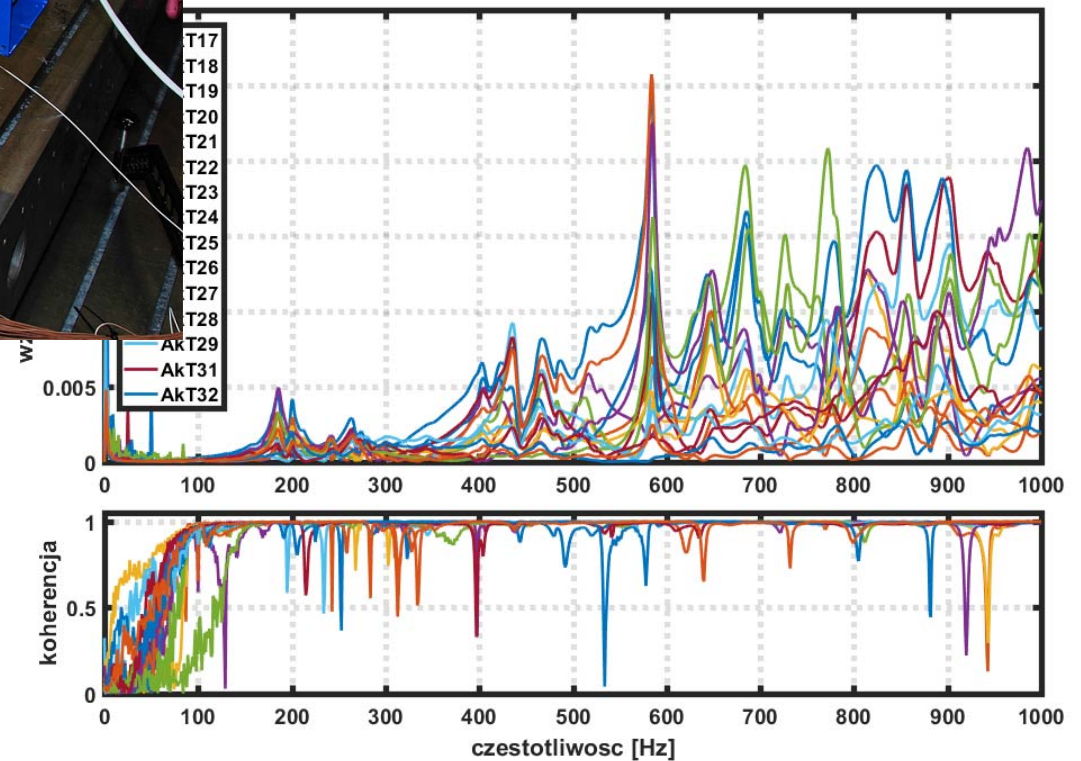
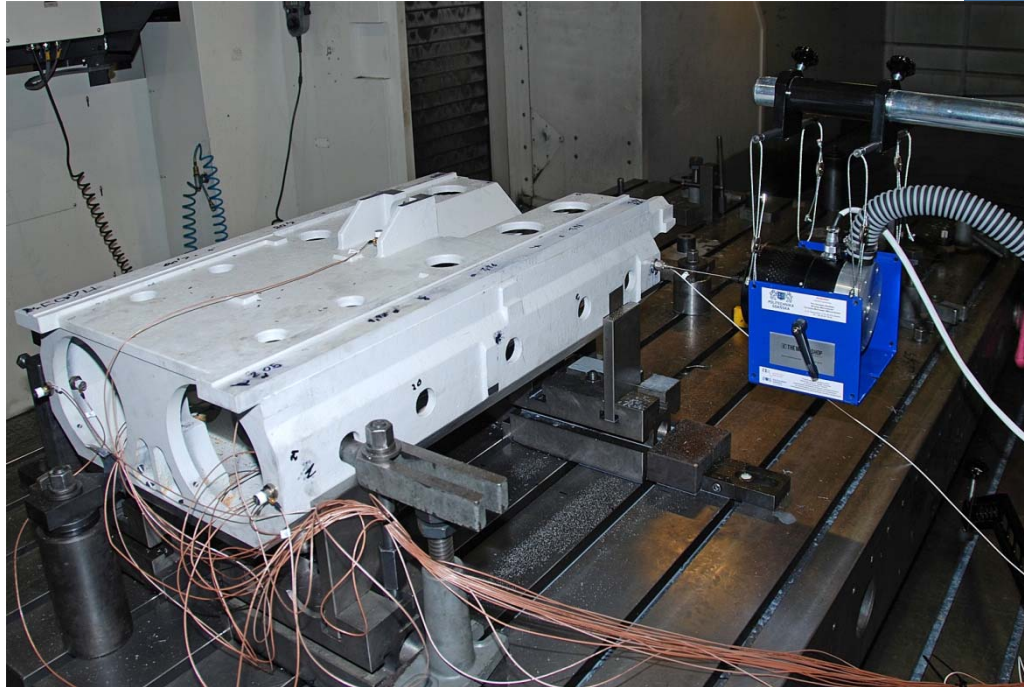




Experimental Modal Analysis



Two methods were used:
ERA – Eigenvalue Realisation Algorithm
p-LSCFD – polyreference-Least Squares Complex Frequency Domain

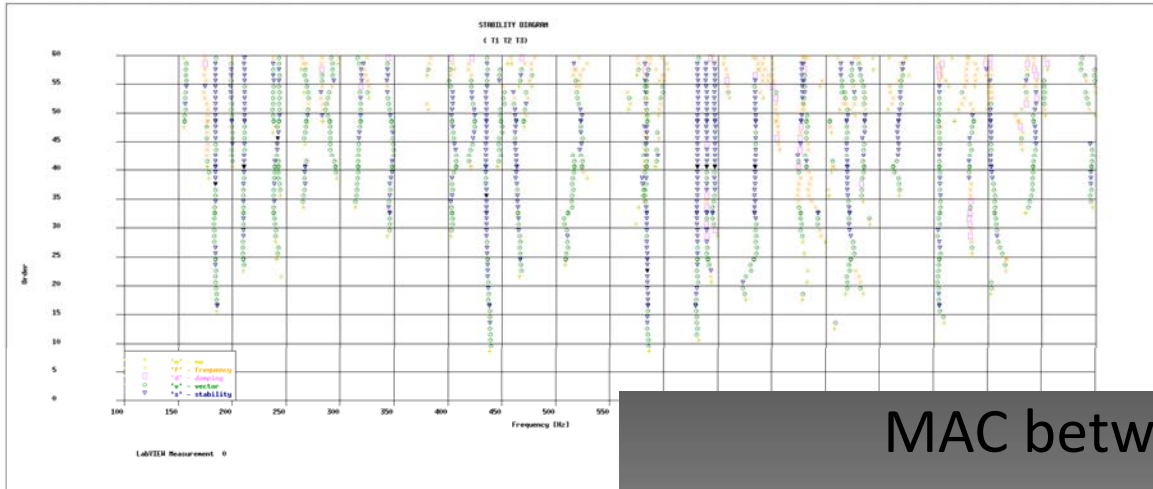
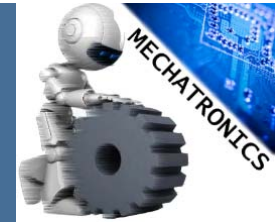




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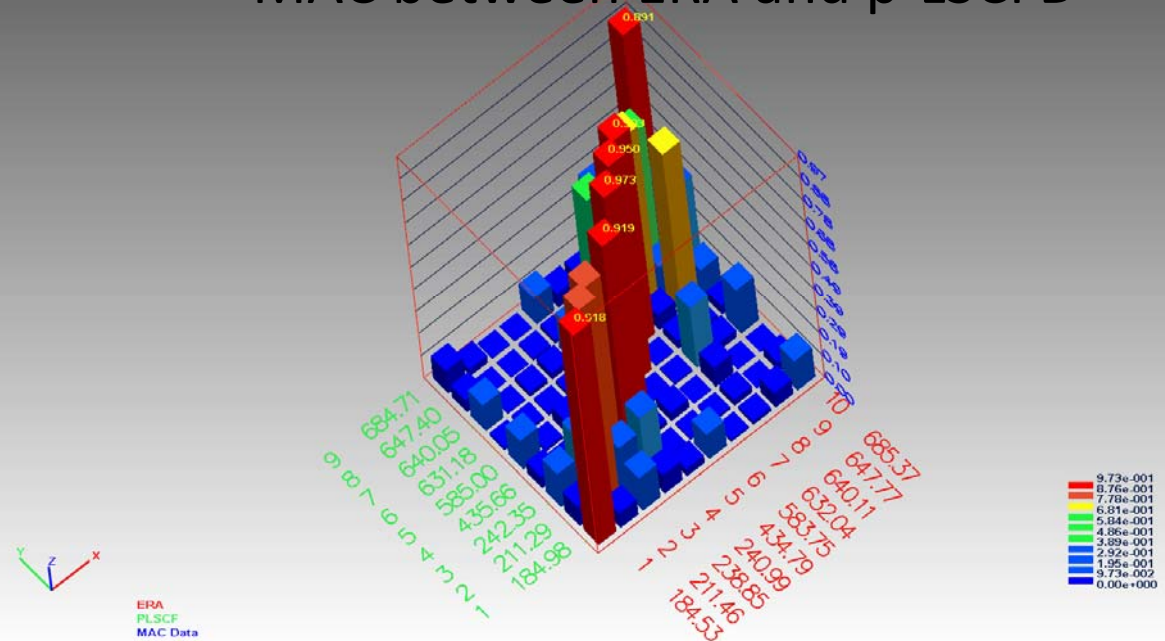
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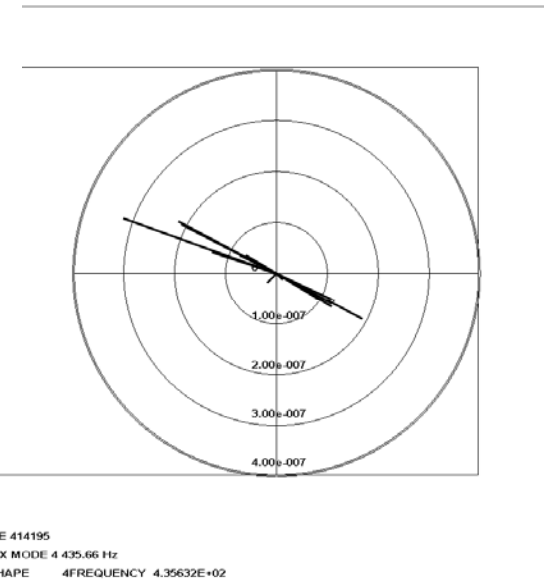
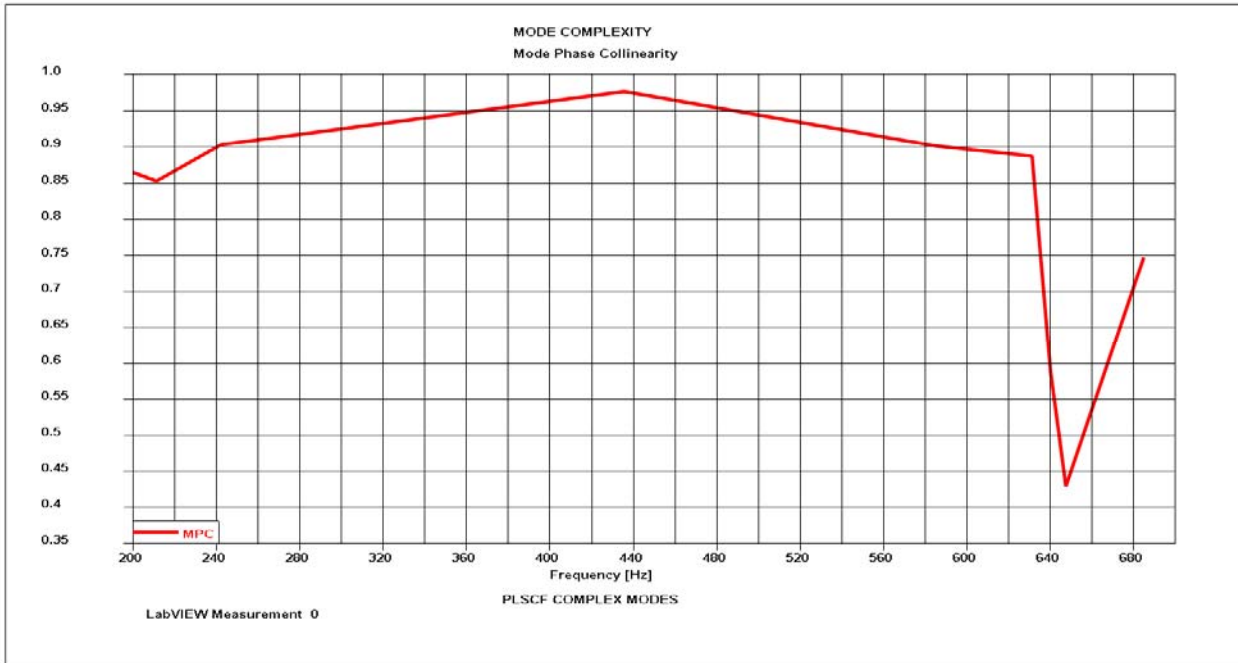
Experimental Modal Analysis



MAC – Modal Assurance Criterion

MAC between ERA and p-LSCFD





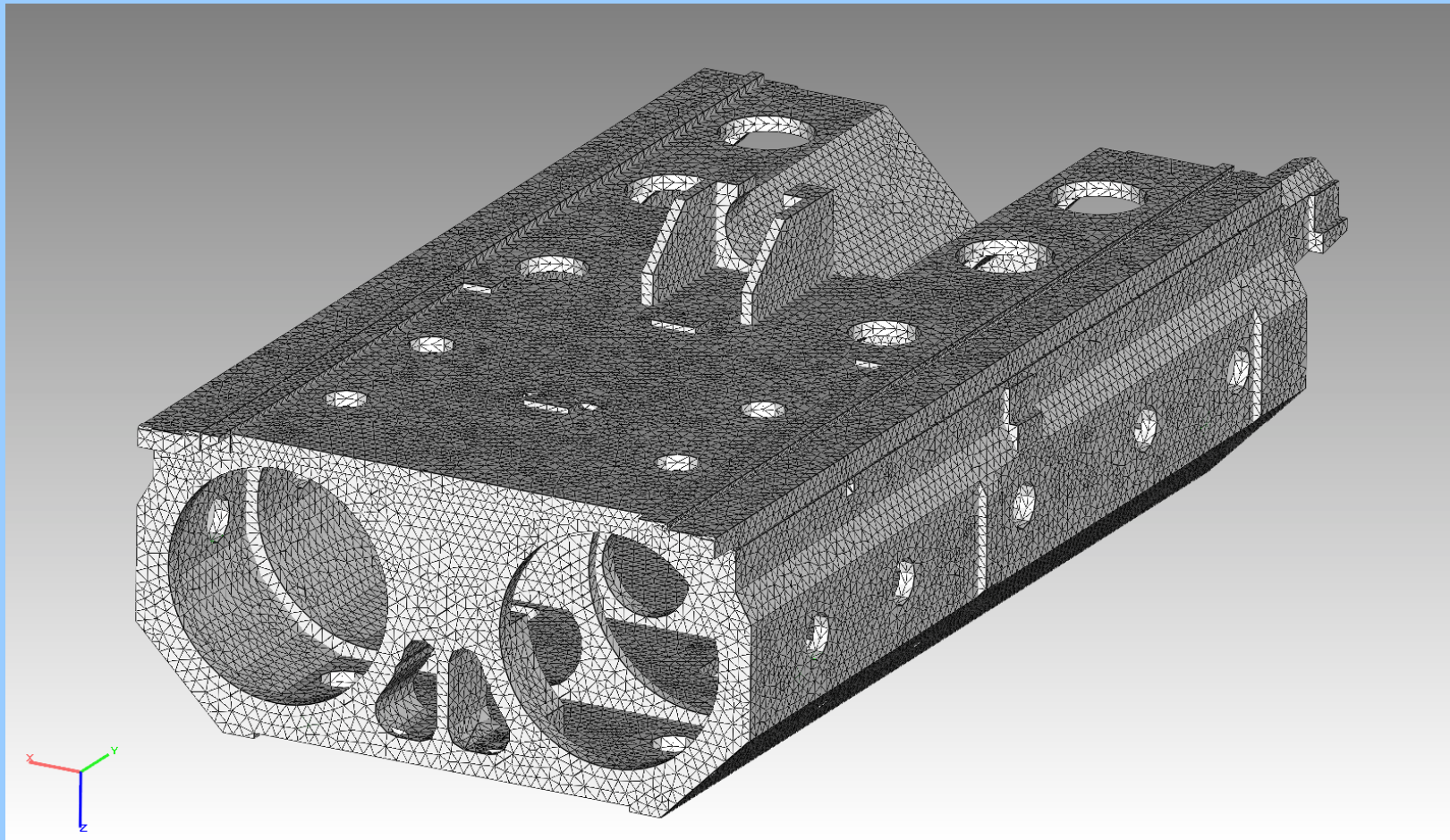
- Mean Phase Collinearity
- MAC
- Frequency



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FEM model

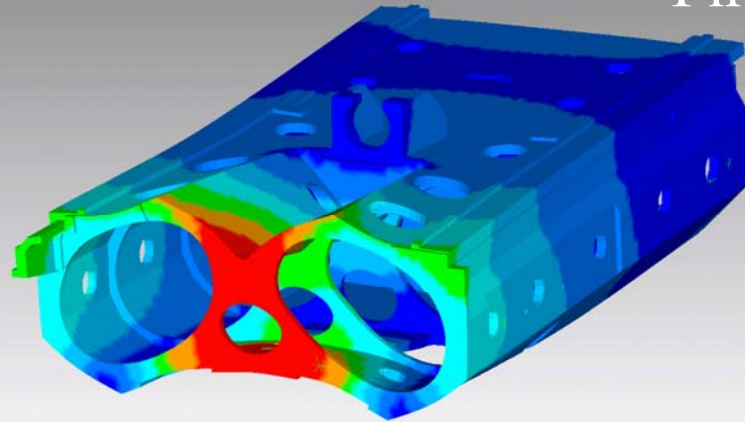


249078 finite elements of the **Tet10** type



First four elastic modes

Animation mode - Frame nr: 16 - from 20



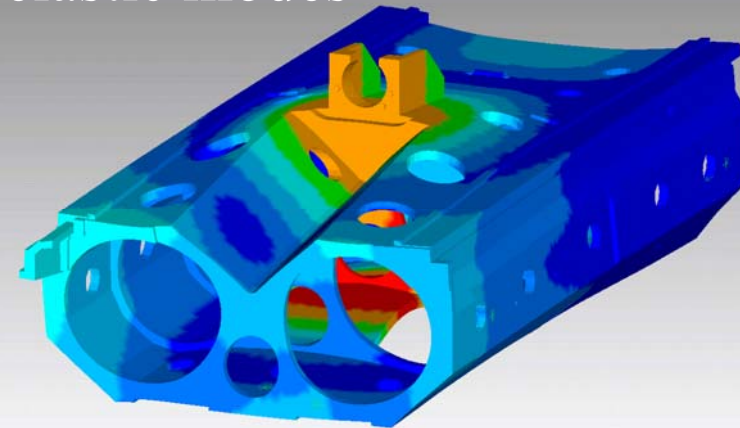
max=7.4390
min= 0.0

7.44e+
6.37e+
5.31e+
4.25e+
3.19e+
2.12e+
1.06e+
0.00e+

Tet10_249k SUBCASE 1 MODE NO 7 395.32Hz Magnitude

Animation mode - Frame nr: 16 - from 20

Animation mode - Frame nr: 16 - from 20



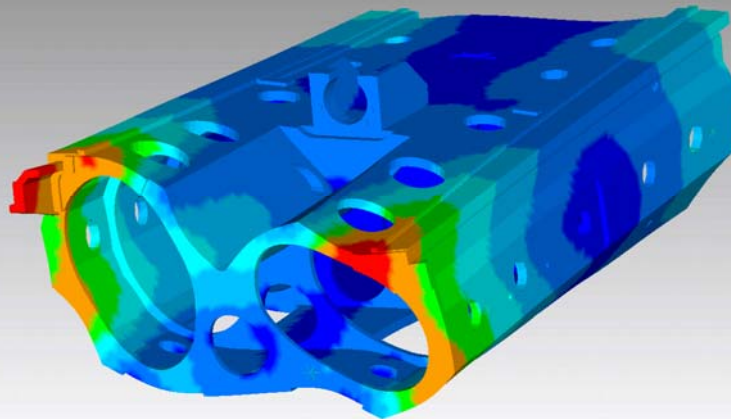
max=7.680954
min= 0.0

7.67e+000
6.57e+000
5.48e+000
4.39e+000
3.29e+000
2.19e+000
1.10e+000
0.00e+000

Tet10_249k SUBCASE 1 MODE NO 8 513.23Hz Magnitude

Animation mode - Frame nr: 16 - from 20

Animation mode - Frame nr: 16 - from 20

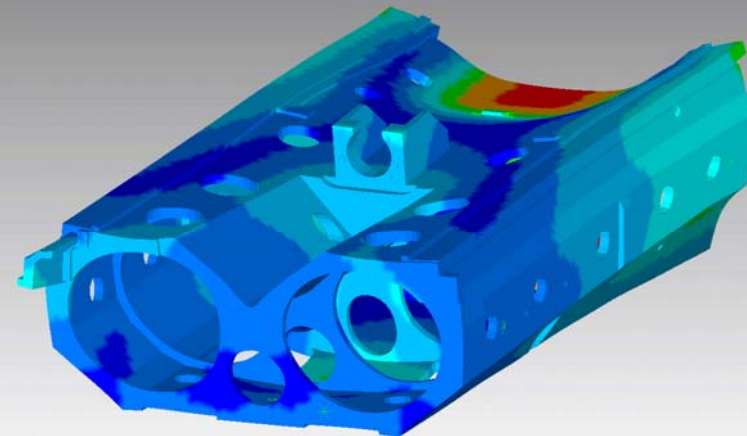


max=7.8963
min= 0.0

7.89e+
6.74e+
5.61e+
4.48e+
3.37e+
2.25e+
1.12e+
0.00e+

Tet10_249k SUBCASE 1 MODE NO 9 585.68Hz Magnitude

Animation mode - Frame nr: 16 - from 20



max= 6.09205
min= 0.0

6.09e+000
5.22e+000
4.35e+000
3.48e+000
2.61e+000
1.74e+000
8.70e-001
0.00e+000

Tet10_249k SUBCASE 1 MODE NO 10 675.84Hz Magnitude



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Supports components



Modified PSO algorithm was used to estimate supports stiffness factors



MAC

0,97	0,02	0,04	0,02	0,09	0	0,11
0,04	0,95	0,11	0	0	0,01	0,03
0,07	0,07	0,95	0,02	0,02	0	0,01
0,25	0,01	0	0,04	0,04	0	0,02
0,03	0,05	0,06	0,89	0,04	0,07	0,12
0,16	0,06	0,03	0,01	0,18	0,03	0
0,07	0,04	0	0,07	0,89	0,03	0,11
0,01	0,02	0	0,01	0,04	0,93	0,2
0,13	0,01	0	0,16	0,03	0,1	0,22
0,01	0,08	0	0,19	0,02	0,3	0,93

Natural frequency

Identification from measurement	178,2	207,9	238,2	-	430,1	-	575,7	618,6	-	721,3
Computation	179,2	207,5	237,8	271,7	429,5	430,6	567,9	616,0	705,0	723,5



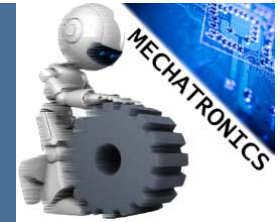
MAC

0,96	0,05	0,08	0,01	0,09	0
0,01	0,98	0,24	0	0,01	0,03
0,08	0,18	0,95	0,03	0,05	0,01
0,2	0	0	0	0,03	0
0,13	0,08	0,03	0,01	0,18	0
0,08	0	0	0,94	0,06	0,01
0,05	0,03	0,03	0,05	0,87	0,01
0	0,03	0	0,01	0,01	0,94

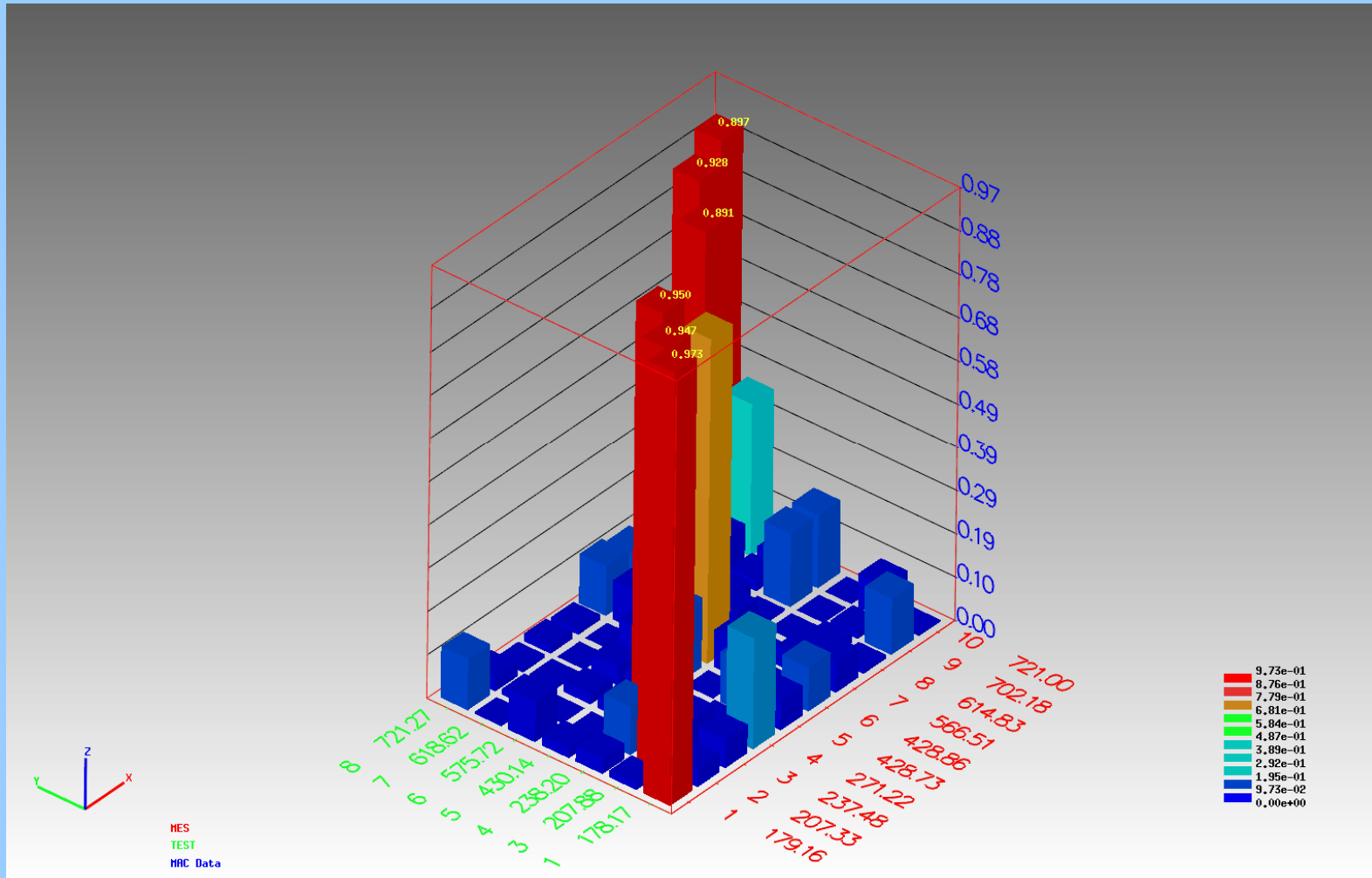
Natural frequency

Identification from measurement	185,0	211,3	242,4	-	-	435,7	585,0	631,2	-	-
Computation	184,6	211,4	242,2	295,5	434,3	434,4	571,5	630,2	710,5	729,5

Model may be subject to change due to pretension.



MAC: measurements and FEM computation





Assumption:

The only one dominant pole exists
in spectrum of the milled workpiece.

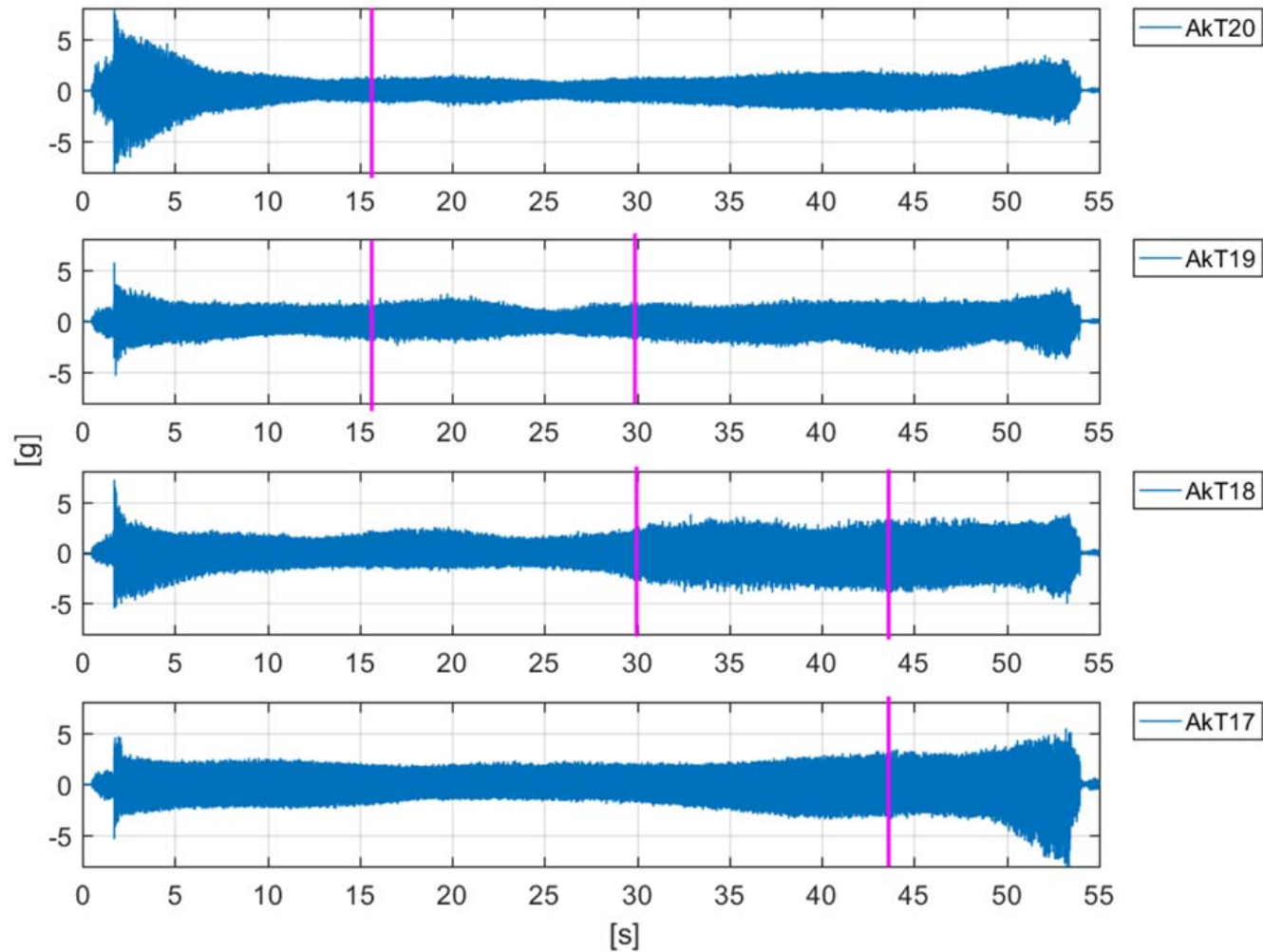
Liao-Young 1996 condition:

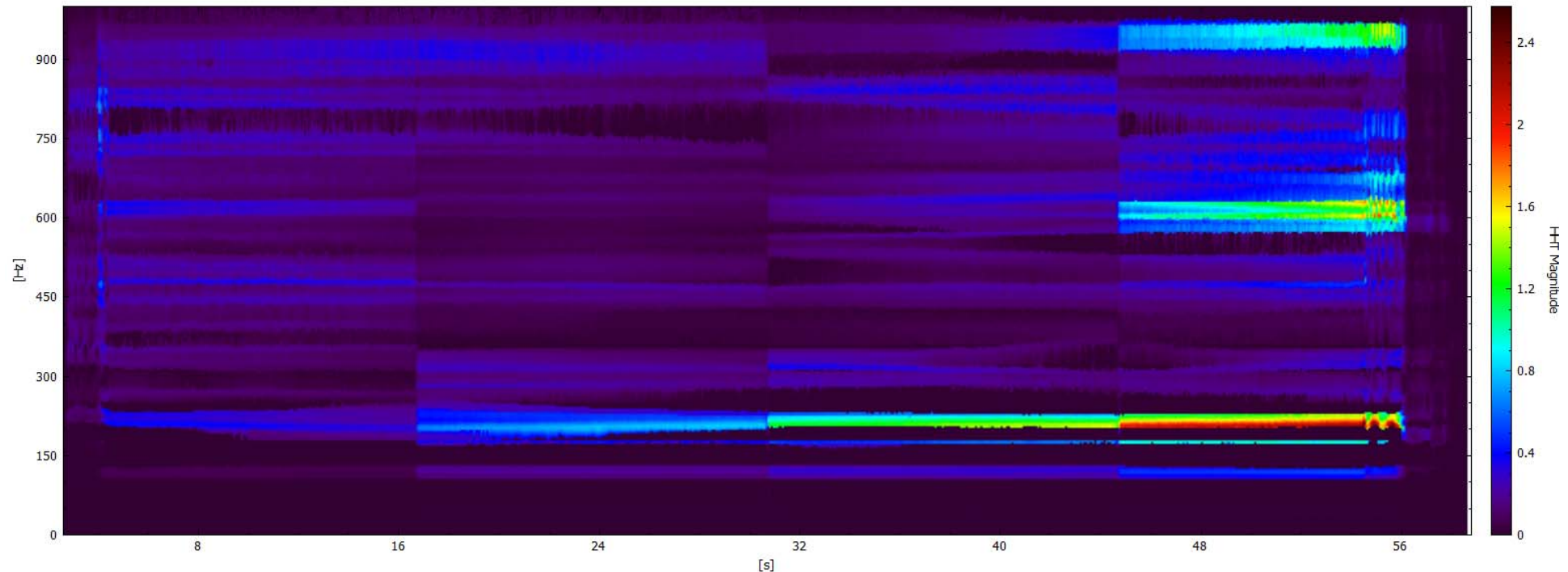
$$\frac{zn_o}{60} = \frac{f_\alpha}{0,25 + k}, \quad k = 0, 1, 2, \dots$$

- f_α – natural frequency of the workpiece [Hz],
- n_o – sought spindle angular velocity [rev/min],
- z – numer of edges of the tool

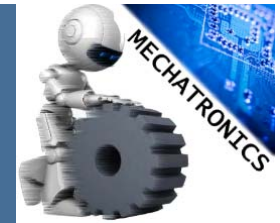


Vibration during the milling process

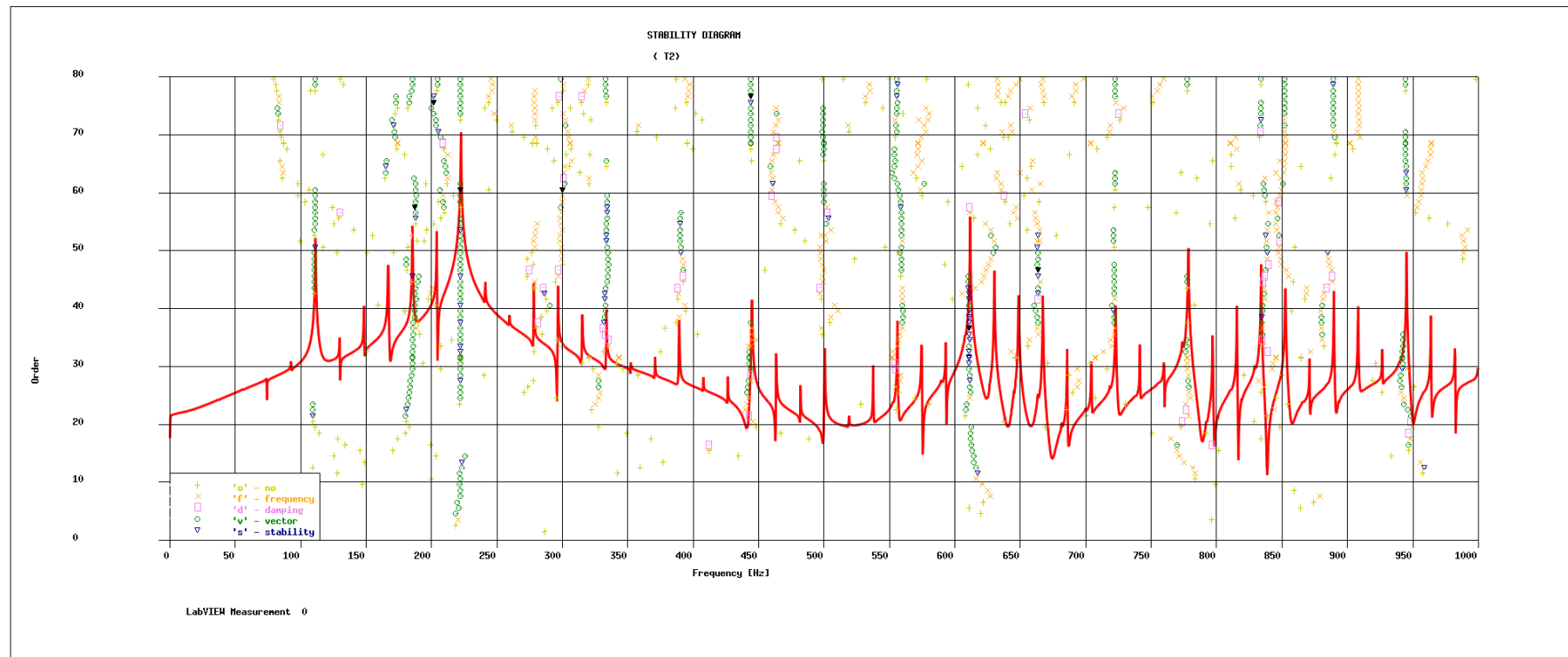




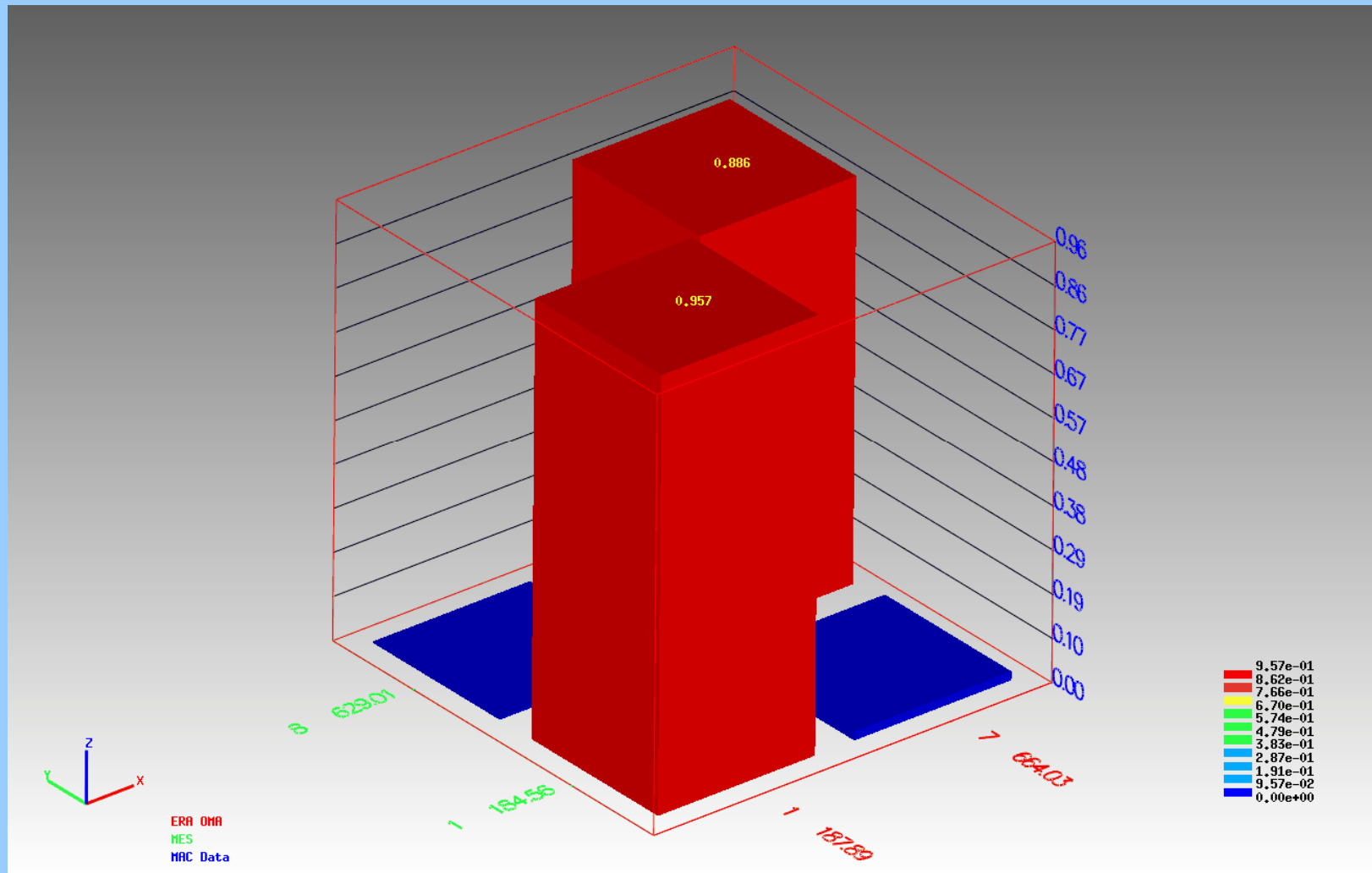
The very well refined face milling process
– nearly nothing happens here ☹️



Power Spectral Density function was computed with the Welch method



Modified ERA – harmonics appear at poles with very small damping



Only two modes very identified correctly



- For well refined machining technology OMA may not be suitable as a main method of identification
- Results from the OMA could be used to track model changes during the process of machining

Thank you for your attention!

